

REPUBLIQUE DU CAMEROUN

Paix – Travail – Patrie

MINISTERE DES ENSEIGNEMENTS SECONDAIRES

DELEGATION REGIONALE POUR LE NORD-OUEST

INSPECTION REGIONALE DE PEDAGOGIE CHARGEE
DES TECHNIQUES INDUSTRIELLES

CONSTRUCTION MECANIQUE

REPUBLIC OF CAMEROON

Peace – Work – Fatherland

MINISTRY OF SECONDARY EDUCATION

REGIONAL DELEGATION FOR
THE NORTH-WEST

REGIONAL INSPECTORATE OF PEDAGOGY IN
CHARGE OF INDUSTRIAL TECHNIQUES

MECHANICAL DESIGN

TEACHING SYLLABUS FOR APPLIED MECHANICS

👉 ***LOWER SIXTH & UPPER SIXTH (ATVE)***

(AM/LY-EPS/F3-ELNI/F2-SMWIP/)

NOVEMBER 2020

TEACHING SYLLABUS FOR APPLIED MECHANICS - ATVE

STATEMENT OF THE COMPETENCE: TO ANALYSE THE BEHAVIOUR AND THE FUNCTIONING OF MACHINE ELEMENTS

MODULE TITLE: APPLIED MECHANICS

CLASS : LOWER SIXTH

WEEKLY HOUR: 3Hrs (2Hours Theory + 1Hour Practicals)

Total theoretical lessons: 68 Hours thus: 44 hours + 12 hours for evaluation + 12 hours for integration activities

Total practical lessons: 34 Hours thus: 22 hours + 6 hours for evaluation + 6 hours for integration activities

MODULE DURATION: 102 hours

COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMANDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
A- STATICS (All trades)				
Identify and represent the common mechanical actions,	NOTION OF VECTOR - Recall on trigonometry - 1st and 2nd degree equations - Vector definition : characteristics - Representation of a vector - Rectangular components of a vector - Vector operations (analytical and graphical): Sum; Multiplication of a vector by a scalar; Scalar or dot product.	Exactitude in: - Vector definition - Decomposition of a vector - Sum and vector products	04 hours	PRACTICALS : 2 Hours - Plotting and vector operations - Vector composition and decomposition;
	FORCE SYSTEMS: - Definition and characteristics - Classification of forces (Contact forces, body forces) TWO DIMENSIONAL FORCE SYSTEMS - Rectangular components - Moment of a force ▪ About a point ▪ About an axis - Couples - Resultants THREE DIMENSIONAL FORCE SYSTEMS - Rectangular components - Moment and couple - Resultants	Exactitude in : - Decomposition of a force - Determination of moments of a force - Determination of rectangular components of a force - Determination of couples and moments of a mechanical action	04 hours	PRACTICALS : 2Hours - Physical effect of forces and moments/couples - Determination of moment of a force about a point and about an axis ;

	– Newton's laws			
	SOLIDS AND MATERIAL SYSTEM Solid: - Mass and centre of gravity Material system - Internal forces & external forces - Principal of mutual action	Exactitude in: - Determination of mass and centre of gravity - Classification and inscription of mechanical actions	02 hours	PRACTICALS: 1 Hour - Solids and material systems discovery; - Rigid bodies and material systems modelling - Characteristics of a rigid body: mass, volume... - Centre of gravity of a rigid body or material system

COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMENDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
Apply the Fundamental Principle of Statics to the equilibrium of rigid bodies subjected to 2, 3 and 4 forces	EQUILIBRIUM OF A RIGID BODY: ANALYTICAL RESOLUTION - System isolation (modelling the action of forces) - The free body diagram (Construction of the free body diagram) - Fundamental Principle of Statics - Categories of equilibrium in 2D - Two and three forces members - Equilibrium in 3D	- Good classification of mechanical actions - Good construction of the free body diagram - Good identification and representation of the components of the mechanical actions of connection and contact;	06 hours	PRACTICALS: 3Hours - Discovery of mechanical actions; - Isolation of a solid or material system; - Construction of the free body diagram - State the principle of mutual actions. - Classify mechanical actions - Discovery of the principle of mutual actions.
	EQUILIBRIUM OF SOLID: GRAPHIC RESOLUTION - Graphic translation of the Fundamental Principle of Statics; - Definition, representation and interpretation of the Force polygon and equilibrium polygon - Applications to coplanar force systems: 2 coplanar forces; 3 coplanar forces; 4 coplanar forces (Cullman's method)	- Good rigid body isolation; - Exact inventory of mechanical action applied to a rigid body; - Good graphic interpretation of the Fundamental Principle of Statics for two and three forces members; - Good graphic resolution; - Correct plotting of the force polygon; - Correct plotting of the equilibrium polygon	06 hours	PRACTICALS : 3Hours - Graphic interpretation of the Fundamental Principle of Statics for cases of 3 and 4 force members; - Plotting of the force polygon and equilibrium polygon - Closing of the polygon - Application of Cullman's method
	STRUCTURES (Only for SMWIP) - Introduction - plane trusses - Method of joints - Method of sections - Frames and machines	- Good plotting of the separate free body diagrams of individual members of combination of members; - Good application of the force and moment equations of equilibrium; - Good determination of the internal forces to a structure;	06 hours	PRACTICALS: 3Hours - Analysis of statically determinate structure - Application of the method of sections - Application of the method of joints - Sample problems on frames and machines

	EQUILIBRIUM OF SOLID BODIES SUBJECTED TO FRICTION - Types of friction : Dry / Fluid friction - Mechanism of dry friction - Mechanism of fluid friction - Static friction - Kinetic friction – friction angle - Notion of cone of static friction	- Good identification and representation of components of mechanical actions; - Good graphic writing/ interpretation of the Fundamental Principle of Statics ; - Good graphic resolution; - Correct plotting of the force polygon;	03 hours	PRACTICALS:2 Hours - Graphic interpretation of the Dry / Fluid friction; - Application of the Fundamental Principle of Statics to solid bodies subjected to friction and writing the equilibriums equations; - Plotting/Interpretation of the force polygon and equilibrium polygon
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COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMENDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
B- KINEMATICS (All trades)				
Determine the kinematic characteristics of rigid bodies in motion with respect to a given reference;	KINEMATICS OF PARTICLE - Introduction - Trajectory - Kinematic vectors: - Velocity vector - Acceleration vector - Representation of kinetic vectors - Tangential and normal components of kinetic vectors - Different types of motions	- Correct determination of the characteristics of the movement - Define the concepts of absolute and relative movement - Identify the main movements of rigid bodies - Indicate the trajectories of the points of rigid bodies - Define the main kinematic quantities - Define the movements of rigid bodies.	04 hours	PRACTICALS : 4Hours - Discovery of the movement of a particle - Kinematic characteristics: abscissa, trajectory, velocity and acceleration; - Discovery of the notion of reference and motion of a rigid body (absolute motion and relative motion);
	STUDY OF PARTICULAR MOTIONS Motion with rectilinear trajectory - General consideration - URM - UVRM Motion with a circular trajectory - General equations - UCM - UVCN	- Indicate the properties of rectilinear motion of rigid bodies - Define velocities and accelerations - Represent and interpret graphs of velocities and accelerations - Define the characteristics of the rotation movement of rigid body - Write the equations of motion - Apply the notions of equiprojectivity and instantaneous center of rotation,	04 hours	
	TRANSLATION AND ROTATION MOTIONS OF A RIGID BODY Notion of rigid body - Translation motion of a rigid body - Rotation motion about a fixed axis	- Determine the velocity vectors by the equiprojectivity method - Determine the velocity vectors by the CIR method, - Write the law of speed composition.	06 hours	PRACTICALS : 3Hours - Discovery / Simulation the translation movement of a rigid body - Main characteristic of translation motion: Abscissa, trajectory, velocity and acceleration of the points belonging to a rigid body in translation.

	GENERAL PLANE MOTION (For all except SMWIP) - Definition of plane motion of solid - Velocity vector fields - Equiprojectivity of velocity vectors - Instantaneous Centre of Rotation; - Composition of motions and velocities; - Composition of the acceleration vectors		06 hours	PRACTICALS : 3Hours - Discovery / Simulation: Rotation movement of a rigid body; - Main kinematic parameters of a rigid body in rotation movement: abscissa, trajectory, velocity and acceleration of the points belonging to a rigid body in rotation.
			06 hours	PRACTICALS : 3Hours - Discovery/Simulation of general plane motion of rigid bodies; - Composition of movements; Velocity field; - Composition of velocity Vectors and accelerations; - Construction of the Instantaneous Centre of Rotation;

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C- STRENGTH OF MATERIAL (Only Mechanical Engineering)				
Sizing of mechanical parts subjected to tensile, compressive or shear stresses	GENERALITIES IN STRENGTH OF MATERIAL - Purpose of strength of material - Support and types of beam - Properties of a plane area: ▪ First moment of area; ▪ Area moment of Inertia or second moment of area - Polar moment of inertia of a surface	- Good calculation of the moment of mass and the second moment of area of a cross-section; - Good definition of the concept of beam. - Good definition of the internal cohesive efforts and stresses; - Good definition and application of the hypotheses of Strength of Material - Good determination of external and internal cohesive efforts for simple stress - Good determination of stresses in a cross-section of a beam - Good determination of deformations - Good representation of internal cohesive efforts diagrams - Good application of the formulas of non failure and rigidity to size the elements - Good identification of the types of stresses	04 hours	PRACTICALS : 4Hours - Beams discovery; - Simulation of an imaginary cut of beam and the behaviour of each part - Analysis and equilibrium of each beam part: Internal cohesive efforts; - Stress calculation. - Plotting and interpretation graph tests - Sizing elements subjected to tension , compression and shearing
	STRESSES IN A BEAM - Hypotheses in strength of material - External and Internal forces ; - Simple stresses in a beam: Normal, shear, bearing, torsional and bending stresses.		04 hours	
	AXIALLY LOADED MEMBERS - Stress and strain ; - Tensile test - Relation between stress and strain: Hooke's law and Young' modulus of elasticity, - Poisson's ratio: lateral strain - Concentration of stress - Tensile/compressive strength condition;		06 hours	PRACTICALS: 3Hours - Tests /Simulation ; tensile – compression stress; - Diagrams of cohesive efforts; - Normal stress; - HOOKE's law: Strength condition and rigidity;

	SHEARING - Shear stress - Shear deflection - Relation between shear stress and shear strain - Shear strength condition - Modulus of rigidity		04 hours	PRACTICALS : 2Hours - Tests /Simulation ; shear stress; - Diagrams of cohesive efforts; - Tangential stress; - HOOKE's law: Strength condition and rigidity;
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COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMANDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
Sizing of mechanical parts subjected to tensile, compressive or shear stresses	TORSION - Definition - Unit angle of twist - Stress distribution in the cross section; - Twisting (torsional) moment (torque, torsional shear stress): - Relation between: ▪ Twisting moment and unit angle of twist ▪ Twisting moment and shear stress (rigidity) - Stress concentration - Torsion strength condition.	- Good determination of the external and internal cohesive efforts and stress analysis - Good representation of the diagrams of internal cohesive efforts and stresses	06 hours	PRACTICALS : 3Hours - Test/simulation of a torsion stress ; - Internal cohesive efforts and Deformation limitations ; - Normal and shear stress; - Law of HOOKE : Strength Condition and rigidity ;
	- Definition - Representation of a loaded beam - Equations of the shearing effort and bending moment along the beam - Bending moment and shearing forces diagrams - Maximum bending moment - Point, uniformly, and combined loadings. - Determination of the maximum bending moment - Direct (axial) stress in beams - Shear stress in beams - Stress concentration - Representation of stress distribution in the cross section of a beam. - Bending strength condition. - Deflection of a beam.	- Good calculation of the moment of mass and the second moment of area of a cross-section; Good definition and application of the hypotheses of strength of material - Good determination of external and internal cohesive efforts - Good determination of stresses in a cross section of beam - Good representation of the diagrams of the internal cohesive efforts and stresses: - Correct sizing of a beam.	06 hours	PRACTICALS : 3Hours - Test/simulation of a cross-bending stress ; - Internal cohesive efforts and deformation limitations ; - Normal and shear stress; - Law of HOOKE : - Bending strength Condition and rigidity

COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMENDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
Sizing of mechanical parts subjected to combined stresses	COMBINED STRESSES - Definition : - External mechanical actions - Internal cohesive mechanical action	- Good calculation of the moment of mass and the second moment of area of a cross-section; Good definition and application of the hypotheses of strength of material - Good determination of external and internal cohesive efforts - Good determination of stresses in a cross section of beam - Good representation of the diagrams of the internal cohesive efforts and stresses: - Correct dimensioning of a beam.	6 hours	PRACTICAL WORK: 3Hours - Test/simulation of traction (compression) and bending combined stresses in a beam; - Internal cohesive efforts, moment and deformation ; - Equivalent efforts and moments - Equivalent normal and shear stresses;
	BENDING +TENSION / COMPRESSION - Bending moment and equivalent stress - Strength condition - Stress diagrams		6 hours	PRACTICALS : 3Hrs - Test/simulation of Bending and Twist combined stresses in a beam; - Internal cohesive efforts, moments and deformation ; - Equivalent efforts and moments - Equivalent normal and shear stresses;
	BENDING + TORSION - Bending moment and normal equivalent stress - Strength condition and rigidity ;		4 hours	PRACTICALS: 2Hrs - Test/simulation of a combined stress of cross-bending + torsion ; - Internal cohesive efforts ; - Equivalent efforts and moments - Equivalent normal and shear stresses; - Law of HOOKE : Strength Condition and rigidity

COMPETENCE ELEMENTS	CONTENTS / LESSONS	EVALUATION INDICATORS	TIME VOLUME	RECOMMANDATIONS From real or virtual mechanisms of the environment of the trade/specialty,
D- DYNAMICS (All trades)				
Apply the fundamental law of dynamics in Galilean reference to determine the kinematics and dynamic parameters of a rigid body in rectilinear motion or rotation about a fixed axis compared with a given reference.	DYNAMICS OF A RIGID BODY IN TRANSLATION - Newton's laws of motion - Inertia and mass of rigid body in translation; - Linear momentum of a rigid body in translation; - Fundamental Principle of Dynamics in translation	- Good calculation of the moments of inertia of rigid bodies, linear and angular momentums - Good application of the Fundamental Principle of Dynamics to a rigid body in rectilinear and rotation motions	4 hours	PRACTICALS : 4Hrs - Simulation of the relation force /couple and movement : - Linear momentum/ Angular momentum - Relation force-acceleration ; - Simulation of a rigid body in rectilinear motion or rotation motion about an axis, - Simulation of the relation forces /couple and velocity/acceleration: - Determination of the energetic parameters of a rigid body in rectilinear motion or rotation motion about an axis, - Graphs
	DYNAMICS OF THE RIGID BODY IN ROTATION - Inertia and mass of a rigid body in rotation; - Angular momentum of a rotating body; - Moment of inertia of a rigid body about an axis (Huygens's theorem) - Fundamental Principle of Dynamics in rotation		4 hours	
Apply the concepts of Energy, Work and Mechanical Power	WORK DONE BY A MECHANICAL ACTION - Work done by a force in translation - Work done by force in rotation or couple POWER OF A MECHANICAL ACTION - Power in translation - Power in rotation	- Good definition of work, power and energy (potential, kinetic and mechanic) - Good determination of the work and the mechanical power of a force / couple in a rectilinear or rotational movement - Good determination of the efficiency of a mechanism - Good calculation of the energy of a rigid body in rotation or in rectilinear translations - Good application of the principle of conservation of mechanical energy	04 hours	PRACTICALS : 4Hrs - Simulation of a rigid body in rectilinear motion or rotation motion about an axis, - Simulation of the relation forces /couple and velocity/acceleration: - Determination of the energetic parameters of a rigid body in rectilinear motion or rotation motion about an axis,
	ENERGIES - Potential Energy : Definition, Variation - Kinetic energy of a rigid body in translation, /in rotation : Definition, Variation - Mechanical Energy of a rigid body in translation, /in rotation: Definition, Variation, Conservation.		04 hours	